

## Toric polymake tutorial

This tutorial will go over the basics of polymake and then focus on the application "fulton" for toric varieties.

### Basics

First let us have a look at how to work with matrices, vectors, etc.

```
In [1]: $A = new Matrix<Rational>([[1,2,3],[4,5,6]]);
        $v = new Vector<Rational>([1,2,3]);
        print $A,"\n";
        print $A * $v,"\n\n";
        print $A * transpose($A),"\n";
        $S = new Set<Integer>([1,2,3]);
        $S2 = new Set<Integer>([2,3,4]);
        print $S * $S2,"\n";
        print $S + $S2,"\n";
        print $S - $S2,"\n";
```

```
Out[1]: 1 2 3
        4 5 6
```

```
14 32
```

```
14 32
32 77
```

```
{2 3}
{1 2 3 4}
{1}
```

Now we use polymake's `cube` command to make a polytope that we will use for the first part of the demo. To see what this command does, use the built-in help. In the terminal, you can use the `F1` key instead.

```
In [2]: $c = cube(2,1,0);
help "cube".
```

```
Out[2]: functions/Producing regular polytopes and their g
eneralizations/cube:
cube<Scalar>(d; x_up, x_low, Options) -> Polytope
<Scalar>
```

Produce a  $d$ -dimensional cube.  
Regular polytope corresponding to the Coxeter group of type  $B_{d-1} = C_{d-1}$ .

The bounding hyperplanes are  $x_i \leq x_{up}$  and  $x_i \geq x_{low}$ .

Type Parameters:

Scalar Coordinate type of the resulting polytope. Unless specified explicitly, deduced from the type of bound values, defaults to Rational.

Arguments:

Int  $d$  the dimension

Scalar  $x_{up}$  upper bound in each dimension

If we have a variable we can ask for its datatype in the following way:

```
In [3]: print $c->type->full_name;
```

```
Out[3]: Polytope<Rational>
```

One of the main principles of polymake is lazy evaluation. This means that properties are not computed when they are not needed and furthermore they are cached after computation. To get a list of properties that have already been computed use the `->properties()` command. To only get a list of the property names, use `->list_properties()`.

```
In [4]: $c->properties();
print "-----\n" . join("\n" . $c->list_prop
```

```
Out[4]: name: c
type: Polytope<Rational>
description: cube of dimension 2
```

```
CONE_AMBIENT_DIM
3
```

```
CONE_DIM
3
```

```
FACETS
(3) (1 1)
1 -1 0
(3) (2 1)
1 0 -1
```

```
AFFINE_HULL
```

```
VERTICES_IN_FACETS
{0 2}
{1 3}
{0 1}
{2 3}
```

```
BOUNDED
1
```

```
-----
CONE_AMBIENT_DIM
CONE_DIM
FACETS
AFFINE_HULL
VERTICES_IN_FACETS
BOUNDED
```

Using the `->` arrow operator, we can trigger computation of properties. For example we can use it to compute the vertices and facets of our polytope.

```
In [5]: $V = $c->VERTICES;
        print $V;
```

```
Out[5]: 1 0 0
        1 1 0
        1 0 1
        1 1 1
```

```
In [6]: $F = $c->FACETS;
        print $F;
```

```
Out[6]: (3) (1 1)
        1 -1 0
        (3) (2 1)
        1 0 -1
```

The matrix `$F` is a sparse matrix. To fill in zeros, we can use `dense`.

```
In [7]: print $F->type->full_name, "\n";
        print dense($F);
```

```
Out[7]: SparseMatrix<Rational, NonSymmetric>
        0 1 0
        1 -1 0
        0 0 1
        1 0 -1
```

```
In [8]: $facet = $F->row(0);
        print $facet + transpose($V);
```

```
Out[8]: 0 1 0 1
```

```
In [9]: print $F + transpose($V);
```

```
Out[9]: 0 1 0 1
        1 0 1 0
        0 0 1 1
        1 1 0 0
```

In [10]: `$c->SVTSHAL.`

Out[10]: polymake: used package threejs  
 Three.js is a lightweight cross-browser JavaScript library/API used to create and display animated 3D computer graphics on a Web browser.  
 See <http://github.com/mrdoob> (<http://github.com/mrdoob>) for the source code.

In [11]: `$c->SHASSE_DIAGRAM->SVTSHAL.`

Out[11]: polymake: used package tikz  
 TikZ, a graphical toolkit for LaTeX.  
<http://pgf.sourceforge.net>. (<http://pgf.sourceforge.net>.)

In [12]: `print "Reflexive? ", $c->REFLEXIVE, "\n";  
 print "Smooth? ", $c->SMOOTH, "\n";  
 print "Normal? ", $c->NORMAL, "\n";`

Out[12]: polymake: used package lrs  
 Implementation of the reverse search algorithm of Avis and Fukuda.  
 Copyright by David Avis.  
<http://cgm.cs.mcgill.ca/~avis/C/lrs.html> (<http://cgm.cs.mcgill.ca/~avis/C/lrs.html>)

Reflexive?

Smooth? 1

polymake: used package libnormaliz

Normaliz is a tool for computations in affine monoids, vector configurations, lattice polytopes, and rational cones.

Copyright by Winfried Bruns, Bogdan Ichim, Christof Soeger.

<http://www.math.uos.de/normaliz/> (<http://www.math.uos.de/normaliz/>)

Normal? 1

In [13]: `help("SMOOTH").`

Out[13]: objects/Polytope/properties/Lattice points in cones/SMOOTH:  
property SMOOTH : Bool  
Only defined for Polytope::Lattice.  
The polytope is smooth if the associated projective variety is smooth; the determinant of the edge directions is +/-1 at every vertex.

In [14]: `help "DIM".`

Out[14]: There are 4 help topics matching 'DIM':

-----

1: objects/Cone/methods/Geometry/DIM:  
DIM() -> Int

returns the geometric dimension of the cone (inc  
luding the lineality space)  
for the dimension of the pointed part ask for `CONE`  
MBINATORIAL\_DIM

Returns Int

-----

2: objects/Polytope/methods/Geometry/DIM:  
DIM() -> Int

returns the dimension of the polytope

Returns Int

-----

3: objects/Symmetry/QuotientSpace/properties/Combinatorics/DIM:  
property DIM : Int

The dimension of the quotient space, defined to  
be the dimension of the polytope.

-----

4: objects/PointConfiguration/methods/Geometry/DIM:  
DIM() -> Int

Affine dimension of the point configuration.  
Similar to Polytope::DIM.

Returns Int

The save and load commands allow one to write  
and read xml files.

In [15]: `save($c, "square").`

```
In [16]: $cc = load("square.poly");  
print "\n" $cc->list_properties() "\n".
```

```
Out[16]: CONE_AMBIENT_DIM  
CONE_DIM  
FACETS  
AFFINE_HULL  
VERTICES_IN_FACETS  
BOUNDED  
POINTED  
FEASIBLE  
N_FACETS  
FULL_DIM  
N_VERTICES  
VERTICES  
LINEALITY_SPACE  
LINEALITY_DIM  
COMBINATORIAL_DIM  
DUAL_GRAPH  
GRAPH  
HASSE_DIAGRAM  
MONOID_GRADING  
CENTERED  
FAR_FACE  
LATTICE  
GORENSTEIN  
GORENSTEIN_INDEX  
GORENSTEIN_VECTOR  
REFLEXIVE  
SIMPLICIAL  
SIMPLE  
SMOOTH  
HILBERT_BASIS_GENERATORS  
N_HILBERT_BASIS  
LATTICE_POINTS_GENERATORS  
N_LATTICE_POINTS  
NORMAL
```



For many computations there are different algorithms available. Some come from external software, some are built in. The `prefer_now` command will set the preferred algorithm for the current line. For a permanent preference use `prefer`.

```
In [17]: help "prefer_now";
$r=rand_sphere(3,1000,seed=>1); prefer_now("beneath");
$r=rand_sphere(3,1000,seed=>1); prefer_now("cdd");
$r=rand_sphere(3,1000,seed=>1); prefer_now("lrs");
```

```
Out[17]: functions/Basic/prefer_now:
prefer_now(label_expression)
```

The same as `prefer`, but does not store the changes persistently. The lifespan of the new preference order lasts up to the end of the current user cycle (that is, end of user script or interpretation of the current input line in interactive mode).

Arguments:

String label\_expression

1996

1996

1996

```
In [18]: help "beneath_beyond";
```

```
Out[18]: preferences/Convex hull computation/beneath_beyond:
d:
```

Use the sequential (beneath-beyond) convex hull algorithm. It performs well at lower dimensions and produces a triangulation of the polytope as a byproduct.

```
In [19]: help "lrs";
```

```
Out[19]: preferences/Convex hull computation/lrs:
```

Use the reverse search method, as implemented in [wiki:external software#lrslib](#).

Computation are done via rules that compute a set of output properties from a set of input properties. To arrive at a desired property, rules are chained together until one gets a path from the given properties. To see which rules will be applied use the `get_schedule($)` command.

```
In [20]: $c = cube(3);
print join("\\n", $c->list_properties()),"\\n\\n";
$s = $c->get_schedule("HASSE_DIAGRAM");
print $s, "\\n\\n";
print join("\\n", $c->list_properties()), "\\n".
```

```
Out[20]: CONE_AMBIENT_DIM
CONE_DIM
FACETS
AFFINE_HULL
VERTICES_IN_FACETS
BOUNDED
```

```
Polymake::Core::Scheduler::RuleChain=ARRAY(0x80bd7f0)
```

```
precondition : BOUNDED ( POINTED : )
POINTED :
precondition : POINTED ( LINEALITY_DIM, LINEALITY_SPACE : CONE_AMBIENT_DIM )
LINEALITY_DIM, LINEALITY_SPACE : CONE_AMBIENT_DIM
COMBINATORIAL_DIM : CONE_DIM, LINEALITY_DIM
HASSE_DIAGRAM.ADJACENCY, HASSE_DIAGRAM.DECORATION
, HASSE_DIAGRAM.INVERSE_RANK_MAP, HASSE_DIAGRAM.TOP_NODE, HASSE_DIAGRAM.BOTTOM_NODE : RAYS_IN_FACETS,
COMBINATORIAL_DIM
```

Apply the schedule using `->apply($)`.

```
In [21]: $s->apply($c);
print join("\n" $c->list_properties()) "\n".
```

```
Out[21]: CONE_AMBIENT_DIM
CONE_DIM
FACETS
AFFINE_HULL
VERTICES_IN_FACETS
BOUNDED
FEASIBLE
POINTED
N_FACETS
N_VERTICES
FULL_DIM
LINEALITY_DIM
LINEALITY_SPACE
COMBINATORIAL_DIM
HASSE_DIAGRAM
```

## Toric geometry

Toric geometry is handled by polymakes application "fulton".

```
In [22]: application "fulton".
```

```
In [23]: $c = new Cone(INPUT_RAYS=>[[-1,1],[1,1]]);
print $c->SUBLIBERT_BASIS.
```

```
Out[23]: -1 1
0 1
1 1
```

```
In [24]: $toric = $c->TORIC_IDEAL;
print $toric->BINOMIAL_GENERATORS;
print "\n";
print join("\n" @{$toric->GENERATORS}).
```

```
In [25]: $tv = new NormalToricVariety($c);
print "Is smooth? ", $tv->SMOOTH, "\n";
print "Is affine? ", $tv->AFFINE, "\n";
print "Is orbifold? ", $tv->ORBIFOLD, "\n";
print "Is complete? ", $tv->COMPLETE, "\n";
$tv->properties();
```

```
Out[25]: polymake: used package cdd
         cddlib
         Implementation of the double description method
         of Motzkin et al.
         Copyright by Komei Fukuda.
         http://www-oldurls.inf.ethz.ch/personal/fukudak
         /cdd_home/ (http://www-oldurls.inf.ethz.ch/personal/fukudak/cdd_home/)
```

```
Is smooth?
Is affine? 1
Is orbifold? 1
Is complete?
type: NormalToricVariety
```

```
LINEALITY_SPACE
```

```
RAYS
-1 1
1 1
```

```
MAXIMAL_CONES
{0 1}
```

```
INTERSECTION_COMPLEX
type: SimplicialComplex
```

```
LINEALITY_DIM
0
```

```
N_MAXIMAL_CONES
1
```

```
MAXIMAL_CONES_COMBINATORIAL_DIMS
1
```

## Affine toric varieties

Affine toric varieties arise from cones. To dualize a (pointed) cone just construct a new cone switching facets and rays.

```
In [26]: $sigma = new Cone(INPUT_RAYS=>[[1,0,0],[0,1,0],[1,0
$sigmaad = new Cone(INPUT_RAYS=>$sigma->FACETS);
print $sigmaad->HILBERT_BASIS, "\n";
print $sigmaad->TORIC_IDEAL->BINOMIAL_GENERATORS, "\n";
print $sigmaad->TORIC_IDEAL->GENERATORS, "\n";
```

The exponent vectors of the binomials generate the lattice of relations of the Hilbert basis of the dual cone. In particular we have

```
In [27]: $hb = $sigmaad->HILBERT_BASIS;
$binomials = $sigmaad->TORIC_IDEAL->BINOMIAL_GENERATORS;
print $binomials + $hb;
```

## Cyclic quotient singularities

Two-dimensional pointed cones in two-dimensional space can always be generated by two rays in the standard form  $[[1,0],[-q,n]]$  with  $0 < q < n$  and  $q$  and  $n$  coprime.

```
In [28]: $N7Q3 = new CyclicQuotient(N=>7, Q=>3);
print primitive($N7Q3->RAYS);
```

```
Out[28]: 1 0
-3 7
```

CQS are deeply connected with the associated continued fractions.

```
In [29]: $cf = new Vector<Rational>($N7Q3->CONTINUED_FRACTION);
print $cf, "\n";
print $cf->[0] - 1 / ($cf->[1] - 1 / ($cf->[2] - 1 / ...)) "\n";
```

```
Out[29]: 3 2 2
7/3
```

```
In [30]: $dcf = new Vector<Rational>($N7Q3->DUAL_CONTINUED_F
print $dcf, "\n";
print $dcf->[0] - 1 / $dcf->[1] "\n";
```

```
Out[30]: 2 4
         7/4
```

If we start with the Hilbert basis of the dual cone, sorted by first coordinate:

```
In [31]: print $N7Q3->WEIGHT_CONE->HILBERT_BASIS, "\n";
$sorted = new Matrix(sort(@{$N7Q3->WEIGHT_CONE->HIL
print $sorted;
```

```
Out[31]: 0 1
         1 1
         2 1
         7 3

         0 1
         1 1
         2 1
         7 3
```

Then the dual continued fraction expansion of  $n/(n-q)$  gives us relations among these elements:

```
In [32]: print $sorted->[0] + $sorted->[2] == $dcf->[0] * $s
print $sorted->[1] + $sorted->[3] == $dcf->[1] + $s
```

```
Out[32]: 1
         1
```

Q: Derive and prove the general relation formula.

## Projective varieties

Projective toric varieties arise from polytopes. Normal projective toric varieties arise from fans. To construct a projective toric variety, simply take the normal fan of a polytope and give it to the NormalToricVariety constructor.

```
In [33]: $PP2 = new NormalToricVariety(normal_fan(simplex(2))
print $PP2->RAYS;
print $PP2->MAXIMAL_CONES;
```

```
Out[33]: 0 1
          1 0
          -1 -1
          {0 1}
          {0 2}
          {1 2}
```

```
In [34]: $PP2->VISUAL;
```

The Hasse diagram looks as follows:

```
In [35]: $PP2->HASSE_DIAGRAM->VISUAL;
```

Now consider the following two cones:

```
In [36]: $c1 = new Cone(simplex(2));
print $c1->HILBERT_BASIS, "\n";
$c2 = new Cone(simplex(2,2));
print $c2->HILBERT_BASIS, "\n";
```

```
Out[36]: 1 0 0
          1 0 1
          1 1 0

          1 0 0
          1 0 1
          1 0 2
          1 1 0
          1 1 1
          1 2 0
```

Lets look at the associated toric ideals:

```
In [37]: print "C1: ", join("\n", @{$c1->TORIC_IDEAL->GENERATORS});
print "C2: ", join("\n", @{$c2->TORIC_IDEAL->GENERATORS});
```

The first ideal is actually  $\emptyset$ . Both ideals are homogeneous and hence, they define projective varieties.

Q: What are these projective varieties?

### A non-projective toric variety

Not every fan is the normal fan of a polytope. Here we give an example.

```
In [38]: $f = new PolyhedralFan(INPUT_RAYS=>
[[1,0,0],[0,1,0],[-1,-1,-1],
[0,0,1],[2,1,1],[1,2,1],[1,1,2]],
INPUT_CONES=>[[0,1,2],[0,2,3],
[1,2,3],[4,5,6],[0,1,4],[1,3,5],
[0,3,6],[1,4,5],[3,5,6],[0,4,6]]
);
$tv = new NormalToricVariety($f);
print "Projective? ", $tv->PROJECTIVE, "\n";
print "Smooth? ", $tv->SMOOTH, "\n";
print "Complete? ", $tv->COMPLETE, "\n";
```

```
Out[38]: Projective?
Smooth?
Complete? 1
```

```
In [39]: $tv->VISUAL;
```

### Hirzebruch surfaces

Hirzebruch surfaces come from two-dimensional complete fans with exactly four rays. Smoothness makes it possible to bring these fans into a standard form such that we arrive at a one-parameter family.



```
In [40]: $h1 = hirzebruch_surface(1);
         print $h1->DAVS.
```

```
Out[40]: 1 0
         0 1
         -1 1
         0 -1
```

```
In [41]: $h1->VISUAL.
```

```
In [42]: $h2 = hirzebruch_surface(2);
         print $h2->DAVS.
```

```
Out[42]: 1 0
         0 1
         -1 2
         0 -1
```

```
In [43]: $h2->VISUAL.
```

Q: Construct the/an associated polytope.

Q: Prove the standard form for complete smooth fans in two dimensions with exactly four rays.

polymake has a method to reconstruct a polytope from a regular fan / projective toric variety.

```
In [44]: $A = generating_polyhedron_facets($h2);
         print $A.
```

```
Out[44]: 2 1 0
         1 0 1
         1 -1 2
         1 0 -1
```

This polytope has the given fan as a normal fan.

```
In [45]: $P = new Polytope(INEQUALITIES=>$A);
$FF = normal_fan($P);
print $FF->RAYS;
print $FF->MAXIMAL_CONES;
```

```
Out[45]: 1 0
0 1
-1 2
0 -1
{2 3}
{0 3}
{1 2}
{0 1}
```

```
In [46]: $FF->VISUAL;
```

### Simple, not smooth

```
In [47]: $p = new Polytope(POINTS=>[
[1, 0, 0, 0],
[1, 1, 1, 0],
[1, 1, 0, 1],
[1, 0, 1, 1]]);
print "Simple? ", $p->SIMPLE, "\n";
print "Smooth? " $p->SMOOTH, "\n";
```

```
Out[47]: Simple? 1
Smooth?
```

### Non-normal toric varieties

polymake only handles normal toric varieties. Nevertheless we can use it to get at the toric ideal of a non-normal toric variety by giving the semigroup generators directly as a mock Hilbert basis. For example for the Neil parabola use:

```
In [48]: $c = new Cone(HILBERT_BASIS_GENERATORS=>[[[2],[3]],
print $c->TORIC_IDEAL->BINOMIAL_GENERATORS;
print $c->TORIC_IDEAL->GENERATORS;
```

If we build a new cone from this semigroup, we see that it was not saturated. The semigroup generated by 2 and 3 does not come from a cone.

```
In [49]: $cc = new Cone(INPUT_RAYS=>$c->HILBERT_BASIS_GENERA
print $cc->RAYS, "\n";
print $cc->HILBERT_BASIS, "\n";
```

```
Out[49]: 1
         1
```

Q: What are necessary conditions for a semigroup to come from a cone?

### Smooth vs normal

It is an open question by Oda whether smoothness and normality of polytopes are equivalent.

```
In [50]: print $p->VERTICES, "\n";
print "Normal? ", $p->NORMAL, "\n";
print "Smooth? ", $p->SMOOTH, "\n";
```

```
Out[50]: 1 0 0 0
         1 1 1 0
         1 1 0 1
         1 0 1 1

Normal?
Smooth?
```

```
In [51]: help "NORMAL";
         help "SMOOTH".
```

```
Out[51]: objects/Polytope/properties/Lattice points in cones/NORMAL:
         property NORMAL : Bool
         Only defined for Polytope::Lattice.
         The polytope is normal if the cone spanned by P
         x {1} is generated in height 1.
```

```
Depends on:
         4ti2 or libnormaliz
```

```
There are 2 help topics matching 'SMOOTH':
```

```
-----
```

```
1: objects/NormalToricVariety/properties/Algebraic Geometry/SMOOTH:
```

```
property SMOOTH : Bool
```

```
A toric variety is smooth if the fan is smooth.
```

```
Alias for property fan::PolyhedralFan::SMOOTH FAN.
```

```
-----
```

```
-----
```

```
2: objects/Polytope/properties/Lattice points in cones/SMOOTH:
```

```
property SMOOTH : Bool
```

```
Only defined for Polytope::Lattice.
```

```
The polytope is smooth if the associated projective variety is smooth; the determinant of the edge directions is +/-1 at every vertex.
```

```
In [52]: print $c->SUBLINEAR_BASIS.
```

```
Out[52]: 1 0 0 0
         1 0 1 1
         1 1 0 1
         1 1 1 0
         2 1 1 1
```

## Accessing Singular

```
In [53]: $c = new Cone(INPUT_RAYS=>[[-1,1],[0,1],[1,1]]);
         $tv = new NormalToricVariety($c);
         $toric = $c->TORIC_IDEAL.
```

```
In [54]: singular_eval("listvar()");
```

```
Out[54]: polymake: used package singular
Singular is a computer algebra system for polynomial computations, with special emphasis on commutative and non-commutative algebra, algebraic geometry, and singularity theory. It is free and open-source under the GNU General Public Licence.
http://www.singular.uni-kl.de/ (http://www.singular.uni-kl.de/)
```

```
In [55]: $radical = $toric->RADICAL;
print join("\n" @{$radical->GENERATORS});
```

```
In [56]: singular_eval("listvar()");
```

```
In [57]: $ideal = $tv->WEIGHT_CONE->TORIC_IDEAL;
print $ideal;
```

```
In [58]: $cmd = "ring r = 0,(x_0,x_1,x_2),dp;";
print $cmd;
```

```
Out[58]: ring r = 0,(x_0,x_1,x_2),dp;
```

```
In [59]: singular_eval($cmd);
singular_eval("r");
```

```
Out[59]: // coefficients: QQ
// number of vars : 3
//          block  1 : ordering dp
//          : names  x_0 x_1 x_2
//          block  2 : ordering C
```

```
In [60]: singular_eval("int n = nvars(r);");
$n = singular_get_var("n");
print $n "\n";
```

```
Out[60]: 3
```

```
In [61]: singular_eval("poly p = x_2^2-x_0*x_1");
$p = singular_get_var("p");
print $p "\n";
```

```
Out[61]: - x_0*x_1 + x_2^2
```

```
In [62]: load_singular_library("deform.lib");
singular_eval("ideal i = x_0*x_1, x_2;");
singular_eval("def L = versal(i);");
singular_eval("L:");
```

```
Out[62]: [1]:
          // coefficients: QQ
          // number of vars : 4
          //          block  1 : ordering ds
          //                : names    A
          //          block  2 : ordering dp
          //                : names    x_0 x_1 x_2
          //          block  3 : ordering C
[2]:
          // coefficients: QQ
          // number of vars : 4
          //          block  1 : ordering ds
          //                : names    A
          //          block  2 : ordering dp
          //                : names    x_0 x_1 x_2
          //          block  3 : ordering C
          // quotient ring from ideal ...
[3]:
          // coefficients: QQ
          // number of vars : 1
          //          block  1 : ordering ds
          //                : names    A
          //          block  2 : ordering C
[4]:
          // coefficients: QQ
          // number of vars : 4
          //          block  1 : ordering ds
          //                : names    A
          //          block  2 : ordering dp
          //                : names    x_0 x_1 x_2
          //          block  3 : ordering C
```

```
In [ ]: 
```